Listing of Claims:

Please cancel claims 1-5 and 12-20 without prejudice. Please amend claim 6 and add new claims 21-25.

1-5. (Cancelled)

6. (Currently Amended) A method of operating a carbon nanotube head with a disk having tracks, comprising:

locating the carbon nanotube head at a desired track at a rough precision by positioning an actuator to which the carbon nanotube head is attached in relation to the desired track;

determining an offset for a read head of the carbon nanotube head based on the desired track through use of a controller, the controller coupled to the carbon nanotube head, the controller determining an offset responsive to an angle of the actuator;

tracking the track through the read head using the offset;

feeding back an indication of a location of the desired track at a fine precision; adjusting the offset responsive to the feeding back;

adjusting a target of the carbon nanotube head responsive to the feeding back, the adjusting accomplished through deflection of an e-beam of the carbon nanotube head;

writing data to the desired track from a write head of the carbon nanotube head;

reading data from the desired track after writing data to the desired track, the reading occurring prior to the disk rotating through a complete rotation, the data read from locations on the desired track where writing data has occurred immediately preceding the reading data, the

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reading data occurring through use of the read head operating by deflecting the e-beam of the read head responsive to the offset;

wherein:

the carbon nanotube head includes a read head, the read head of the carbon nanotube head including:

a base,

a substrate mounted on the base,

a carbon nanotube fixedly mounted on the substrate,

a housing mounted on the base, the housing enclosing the carbon nanotube,

a gating electrode mounted on the housing;

a focus electrode mounted on the housing;

a tracking electrode mounted on and within the housing,

an acceleration electrode mounted on and within the housing,

an opening in the housing opposite the carbon nanotube,

a boron-nitride window mounted on the housing and completely closing the opening of the housing,

a detection electrode mounted on <u>an external surface of</u> the housing, the detection electrode to detect electrons reflected from a recording medium;

and wherein:

the write head of the carbon nanotube head including:

a base,

a substrate mounted on the base,

a carbon nanotube on the substrate,

a housing mounted on the base, the housing enclosing the carbon nanotube,

a tracking electrode mounted on and within the housing,

an acceleration electrode mounted on and within the housing,

an opening in the housing opposite the carbon nanotube,

a boron-nitride window mounted on the housing and completely closing the

opening of the housing,

a detection electrode mounted on an external surface of the housing;

and wherein:

tracking occurs based on signals received from the detection electrode of the read head;

and

adjusting the target occurs through operation of the tracking electrode of the read head.

7-20. (Cancelled)

21. (New) A method of operating a carbon nanotube head with a disk having tracks,

comprising:

locating the carbon nanotube head at a desired track at a rough precision by positioning

an actuator to which the carbon nanotube head is attached in relation to the desired track;

determining an offset for a read head of the carbon nanotube head based on the desired

track through use of a controller, the controller coupled to the carbon nanotube head, the

controller determining an offset responsive to an angle of the actuator;

tracking the track through the read head using the offset;

feeding back an indication of a location of the desired track at a fine precision;

adjusting the offset responsive to the feeding back;

adjusting a target of the carbon nanotube head responsive to the feeding back, the adjusting accomplished through deflection of an e-beam of the carbon nanotube head;

wherein:

the read head of the carbon nanotube head including:

a base,

a substrate mounted on the base,

a carbon nanotube fixedly mounted on the substrate,

a housing mounted on the base,

a tracking electrode mounted on the housing,

an acceleration electrode mounted on the housing,

a detection electrode mounted on the housing;

and wherein:

tracking occurs based on signals received from the detection electrode;

and

adjusting the target occurs through operation of the tracking electrode.

22. (New) A method of operating a carbon nanotube head with a disk having tracks, comprising:

locating the carbon nanotube head at a desired track at a rough precision;

determining an offset for a read head of the carbon nanotube head based on the desired

track;

tracking the track through the read head using the offset;

feeding back an indication of a location of the desired track at a fine precision; adjusting the offset responsive to the feeding back;

adjusting a target of the carbon nanotube head responsive to the feeding back, the adjusting accomplished through deflection of an e-beam of the carbon nanotube head;

wherein:

the read head of the carbon nanotube head including:

a base,

a substrate mounted on the base,

a carbon nanotube on the substrate,

a housing mounted on the base,

a tracking electrode mounted on the housing,

an acceleration electrode mounted on the housing,

a detection electrode mounted on the housing;

and wherein:

tracking occurs based on signals received from the detection electrode;

and

adjusting the target occurs through operation of the tracking electrode.

23. (New) The method of claim 22, wherein:

the locating the carbon nanotube head at a desired track at a rough precision occurs through positioning an actuator to which the carbon nanotube head is attached.

24. (New) The method of claim 22, wherein:

the determining an offset for a read head based on the desired track occurs through operation of a controller, the controller coupled to the carbon nanotube head.

25. (New) The method of claim 24, wherein:

the controller determines the offset responsive to an angle of an actuator connected to the carbon nanotube head.